

Maps that take lines to conics

V. Timorin*

*Department of Mathematics,
National Research University
Higher School of Economics,
Moscow

October 7, 2011
MI RAS

Some classical theorems

Theorem (Möbius, 1827)

Suppose that $f : \mathbb{R}P^n \rightarrow \mathbb{R}P^n$ is a continuous one-to-one map taking all straight lines to straight lines. Then f is a projective transformation.

Theorem (Möbius, 1820s)

Suppose that $f : S^n \rightarrow S^n$ is a continuous one-to-one map taking all circles to circles. Then f is a Möbius transformation.

By definition, a Möbius transformation is an element of the group generated by inversions.

Some classical theorems

Theorem (Möbius, 1827)

Suppose that $f : \mathbb{R}P^n \rightarrow \mathbb{R}P^n$ is a continuous one-to-one map taking all straight lines to straight lines. Then f is a projective transformation.

Theorem (Möbius, 1820s)

*Suppose that $f : S^n \rightarrow S^n$ is a continuous one-to-one map taking all circles to circles. Then f is a **Möbius transformation**.*

By definition, a Möbius transformation is an element of the group generated by inversions.

Theorem (von Staudt)

The continuity assumption in theorems of Möbius is superfluous.

Theorem (local version)

If $U \subset \mathbb{RP}^n$ is a connected open set, and $f : U \rightarrow \mathbb{RP}^n$ is a continuous one-to-one map such that, for every line L , the set $f(U \cap L)$ is a subset of a line, then f is the restriction of some projective transformation.

There is also a local version of Möbius' theorem about circles.

Karl Georg Christian von Staudt 1798 - 1867



Classical geometric structures

Definition

A **projective structure** on a manifold M of dimension n is a family of curves \mathcal{C} in M that is locally modeled by the family of all lines in \mathbb{R}^n .

Then M can be covered with charts so that all the transition maps are projective. This follows from Möbius' theorem.

Classical geometric structures

Definition

A **projective structure** on a manifold M of dimension n is a family of curves \mathcal{C} in M that is locally modeled by the family of all lines in \mathbb{R}^n .

Then M can be covered with charts so that all the transition maps are projective. This follows from Möbius' theorem.

A problem

Problem

Describe all (sufficiently smooth) (one-to-one) maps from an open subset of \mathbb{RP}^n to an open subset of S^n that take all lines to circles.

Definition

We say that a map $f : U \subset \mathbb{RP}^n \rightarrow V \subset S^n$ **takes all lines to circles** if the image of each straight line segment contained in U is an arc of Euclidean circle contained in V .

Problem

Describe all maps that take lines to conics, to plane curves etc.

A problem

Problem

Describe all (sufficiently smooth) (one-to-one) maps from an open subset of \mathbb{RP}^n to an open subset of S^n that take all lines to circles.

Definition

We say that a map $f : U \subset \mathbb{RP}^n \rightarrow V \subset S^n$ **takes all lines to circles** if the image of each straight line segment contained in U is an arc of Euclidean circle contained in V .

Problem

Describe all maps that take lines to conics, to plane curves etc.

A problem

Problem

Describe all (sufficiently smooth) (one-to-one) maps from an open subset of $\mathbb{R}P^n$ to an open subset of S^n that take all lines to circles.

Definition

We say that a map $f : U \subset \mathbb{R}P^n \rightarrow V \subset S^n$ **takes all lines to circles** if the image of each straight line segment contained in U is an arc of Euclidean circle contained in V .

Problem

Describe all maps that take lines to conics, to plane curves etc.

Motivations

- **Geometrization**: how to define transition functions between charts carrying different geometric structures?
- **Nomography**: how to transform nomograms with aligned points into circular nomograms?
- **Blaschke's problem**: how to describe all hexagonal 3-webs of circles?
- **Architecture**: how to build free-form structures from arcs of circles? (M. Skopenkov, H. Pottmann, L. Shi, Th. Nilov, Ph. Grohs)
- **Completely integrable systems**: (V. Matveev, S. Tabachnikov)

Motivations

- **Geometrization**: how to define transition functions between charts carrying different geometric structures?
- **Nomography**: how to transform nomograms with aligned points into circular nomograms?
- **Blaschke's problem**: how to describe all hexagonal 3-webs of circles?
- **Architecture**: how to build free-form structures from arcs of circles? (M. Skopenkov, H. Pottmann, L. Shi, Th. Nilov, Ph. Grohs)
- **Completely integrable systems**: (V. Matveev, S. Tabachnikov)

Motivations

- **Geometrization**: how to define transition functions between charts carrying different geometric structures?
- **Nomography**: how to transform nomograms with aligned points into circular nomograms?
- **Blaschke's problem**: how to describe all hexagonal 3-webs of circles?
- **Architecture**: how to build free-form structures from arcs of circles? (M. Skopenkov, H. Pottmann, L. Shi, Th. Nilov, Ph. Grohs)
- **Completely integrable systems**: (V. Matveev, S. Tabachnikov)

Motivations

- **Geometrization**: how to define transition functions between charts carrying different geometric structures?
- **Nomography**: how to transform nomograms with aligned points into circular nomograms?
- **Blaschke's problem**: how to describe all hexagonal 3-webs of circles?
- **Architecture**: how to build free-form structures from arcs of circles? (M. Skopenkov, H. Pottmann, L. Shi, Th. Nilov, Ph. Grohs)
- **Completely integrable systems**: (V. Matveev, S. Tabachnikov)

Motivations

- **Geometrization**: how to define transition functions between charts carrying different geometric structures?
- **Nomography**: how to transform nomograms with aligned points into circular nomograms?
- **Blaschke's problem**: how to describe all hexagonal 3-webs of circles?
- **Architecture**: how to build free-form structures from arcs of circles? (M. Skopenkov, H. Pottmann, L. Shi, Th. Nilov, Ph. Grohs)
- **Completely integrable systems**: (V. Matveev, S. Tabachnikov)

Wilhelm Blaschke 1885 - 1962



Some other classical theorems

Theorem (Beltrami, 1880s)

*Let g be a Riemannian metric on an open subset of $\mathbb{R}P^n$ such that all geodesics are straight line segments. Then g is a **classical metric**, i.e. has constant sectional curvature.*

Theorem (Segre, 1950s)

*Let g be a Riemannian metric on an open subset of S^2 such that all geodesics are arcs of circles. Then g is a **classical metric**, i.e. has constant Gaussian curvature.*

Some other classical theorems

Theorem (Beltrami, 1880s)

*Let g be a Riemannian metric on an open subset of $\mathbb{R}P^n$ such that all geodesics are straight line segments. Then g is a **classical metric**, i.e. has constant sectional curvature.*

Theorem (Segre, 1950s)

*Let g be a Riemannian metric on an open subset of S^2 such that all geodesics are arcs of circles. Then g is a **classical metric**, i.e. has constant Gaussian curvature.*

Beniamino Segre 1903–1977



Another problem

Remark

Note that the theorem of Segre is only about dimension 2!

Problem

Describe all Riemannian metrics on an open subset of S^n such that all geodesics are arcs of circles.

Another problem

Remark

Note that the theorem of Segre is only about dimension 2!

Problem

Describe all Riemannian metrics on an open subset of S^n such that all geodesics are arcs of circles.

Motivation: Nomography

Nomograms:

A **nomogram** is a planar picture representing a function of many variables. Usually, it consists of several curves equipped with scalings. One uses a straightedge or a compass to read the output.

Compass vs Straightedge:

Compass is more accurate than a straightedge, because even a deformed compass draws round circles. Thus **circular nomograms** are more practical, while **nomograms with aligned points** (those using a straightedge) are easier theoretically.

Motivation: Nomography

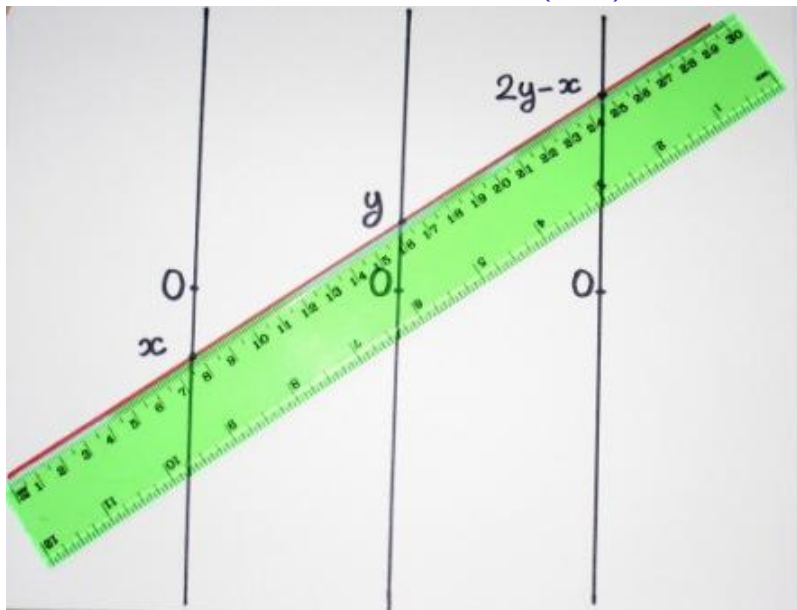
Nomograms:

A **nomogram** is a planar picture representing a function of many variables. Usually, it consists of several curves equipped with scalings. One uses a straightedge or a compass to read the output.

Compass vs Straightedge:

Compass is more accurate than a straightedge, because even a deformed compass draws round circles. Thus **circular nomograms** are more practical, while **nomograms with aligned points** (those using a straightedge) are easier theoretically.

A simple nomogram computing $(x, y) \mapsto 2y - x$



A problem

Problem

Describe all (sufficiently smooth) (one-to-one) maps from an open subset of \mathbb{RP}^n to an open subset of S^n that take all lines to circles.

Definition

We say that a map $f : U \subset \mathbb{RP}^n \rightarrow V \subset S^n$ **takes all lines to circles** if the image of each straight line segment contained in U is an arc of Euclidean circle contained in V .

Results in dimensions 2 and 3

Theorem (Khovanskii, 70s)

Suppose that a diffeomorphism $f : U \subset \mathbb{RP}^2 \rightarrow V \subset S^2$ takes all lines to circles. Then $f = M \circ \phi \circ P$, where $P : \mathbb{RP}^2 \rightarrow \mathbb{RP}^2$ is a projective transformation, $M : S^2 \rightarrow S^2$ is a Möbius transformation, and $\phi \in \{\phi_{Euc}, \phi_{sph}, \phi_{hyp}\}$ corresponds to a **classical model of a classical geometry** (i.e. Euclidean, spherical or hyperbolic geometry).

Theorem (Izadi, 2003)

The same result is true for diffeomorphisms $f : U \subset \mathbb{RP}^3 \rightarrow V \subset S^3$.

Results in dimensions 2 and 3

Theorem (Khovanskii, 70s)

Suppose that a diffeomorphism $f : U \subset \mathbb{RP}^2 \rightarrow V \subset S^2$ takes all lines to circles. Then $f = M \circ \phi \circ P$, where $P : \mathbb{RP}^2 \rightarrow \mathbb{RP}^2$ is a projective transformation, $M : S^2 \rightarrow S^2$ is a Möbius transformation, and $\phi \in \{\phi_{Euc}, \phi_{sph}, \phi_{hyp}\}$ corresponds to a **classical model of a classical geometry** (i.e. Euclidean, spherical or hyperbolic geometry).

Theorem (Izadi, 2003)

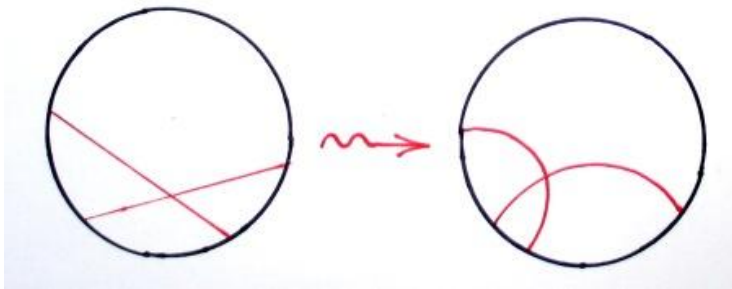
The same result is true for diffeomorphisms $f : U \subset \mathbb{RP}^3 \rightarrow V \subset S^3$.

The maps ϕ_{Euc} , ϕ_{sph} , ϕ_{hyp}

$$\phi_{Euc} = id, \quad \phi_{sph}^{-1}(x, y) = \frac{(x, y)}{1 + x^2 + y^2}, \quad \phi_{hyp}^{-1}(x, y) = \frac{(x, y)}{1 - x^2 - y^2}.$$

Example

The map ϕ_{hyp} establishes an isomorphism between the Klein model and the Poincaré model of the classical hyperbolic geometry.



Quaternionic Hopf fibrations

Definition

Consider the map

$$\mathbb{H}^2 - 0 \rightarrow \mathbb{HP}^1, \quad (q_1, q_2) \mapsto [q_1 : q_2],$$

where \mathbb{HP}^1 is the (left or right) quaternionic projective line. Note that $\mathbb{HP}^1 = S^4$. This map factors through the real projectivization

$$\mathbb{H}^2 - 0 \rightarrow \mathbb{RP}^7$$

to give a map

$$\mathbb{RP}^7 \rightarrow S^4$$

called a **quaternionic Hopf fibration**.

Results in dimension 4

Theorem

Let $f : U \subset \mathbb{RP}^4 \rightarrow V \subset S^4$ be a diffeomorphism taking all lines to circles. Then

- either $f = M \circ \phi \circ P$, where $P : \mathbb{RP}^4 \rightarrow \mathbb{RP}^4$ is projective, $M : S^4 \rightarrow S^4$ is Möbius and $\phi \in \{\phi_{Euc}, \phi_{sph}, \phi_{hyp}\}$
- or f is of the form $\mathbb{RP}^4 \hookrightarrow \mathbb{RP}^7 \rightarrow S^4$, where the first arrow is a projective embedding, and the second is a quaternionic Hopf fibration.

There are much more maps of the second kind.

Results in dimension 4

Theorem

Let $f : U \subset \mathbb{RP}^4 \rightarrow V \subset S^4$ be a diffeomorphism taking all lines to circles. Then

- either $f = M \circ \phi \circ P$, where $P : \mathbb{RP}^4 \rightarrow \mathbb{RP}^4$ is projective, $M : S^4 \rightarrow S^4$ is Möbius and $\phi \in \{\phi_{\text{Euc}}, \phi_{\text{sph}}, \phi_{\text{hyp}}\}$
- or f is of the form $\mathbb{RP}^4 \hookrightarrow \mathbb{RP}^7 \rightarrow S^4$, where the first arrow is a projective embedding, and the second is a quaternionic Hopf fibration.

There are much more maps of the second kind.

Results in dimension 4

Theorem

Let $f : U \subset \mathbb{R}P^4 \rightarrow V \subset S^4$ be a diffeomorphism taking all lines to circles. Then

- either $f = M \circ \phi \circ P$, where $P : \mathbb{R}P^4 \rightarrow \mathbb{R}P^4$ is projective, $M : S^4 \rightarrow S^4$ is Möbius and $\phi \in \{\phi_{Euc}, \phi_{sph}, \phi_{hyp}\}$
- or f is of the form $\mathbb{R}P^4 \hookrightarrow \mathbb{R}P^7 \rightarrow S^4$, where the first arrow is a projective embedding, and the second is a quaternionic Hopf fibration.

There are much more maps of the second kind.

Results in dimension 4

Theorem

Let g be a *Kähler* metric on an open subset of \mathbb{C}^2 such that all geodesics are arcs of circles (or straight segments). Then g has constant *holomorphic sectional curvature*, i.e. g is a “complexification” of one of the classical geometries.

These are: Euclidean geometry, Fubini–Study metric on $\mathbb{C}P^2$, complex hyperbolic geometry.

Higher dimensions

In higher dimensions, the problem is still OPEN, but there are remarkable relations with classical problems in algebra, including:

- Hurwitz problem on sums of squares,
- quadratic maps between spheres,
- fractional quadratic parameterizations of quadrics

Higher dimensions

In higher dimensions, the problem is still OPEN, but there are remarkable relations with classical problems in algebra, including:

- Hurwitz problem on sums of squares,
- quadratic maps between spheres,
- fractional quadratic parameterizations of quadrics

Higher dimensions

In higher dimensions, the problem is still OPEN, but there are remarkable relations with classical problems in algebra, including:

- Hurwitz problem on sums of squares,
- quadratic maps between spheres,
- fractional quadratic parameterizations of quadrics

Results in higher dimensions

Theorem

Suppose that $f : U \subset \mathbb{R}P^n \rightarrow V \subset S^n$ takes all lines *passing through a particular point $p \in U$* to circles. Also, let f be differentiable sufficiently many times and satisfy $\text{rank}(d_p f) > 1$. Then there is a *fractional quadratic* map $Q : \mathbb{R}P^n \dashrightarrow S^m$ such that $f(l) = Q(l)$ for all lines $l \ni p$.

Open problems in algebra

Problem

Describe all *fractional quadratic* maps $\mathbb{R}P^n \dashrightarrow S^m$.

Remark:

This problem is very difficult. A special case of it is the following

Problem (Hurwitz, 1898)

Describe all triples of integers (r, s, n) such that

$$(x_1^2 + \cdots + x_r^2)(y_1^2 + \cdots + y_s^2) = z_1^2 + \cdots + z_n^2,$$

where z_i are some bilinear combinations of x_j and y_k .

Open problems in algebra

Problem

Describe all *fractional quadratic* maps $\mathbb{RP}^n \dashrightarrow S^m$.

Remark:

This problem is very difficult. A special case of it is the following

Problem (Hurwitz, 1898)

Describe all triples of integers (r, s, n) such that

$$(x_1^2 + \cdots + x_r^2)(y_1^2 + \cdots + y_s^2) = z_1^2 + \cdots + z_n^2,$$

where z_i are some bilinear combinations of x_j and y_k .

Open problems in algebra

Problem

Describe all *fractional quadratic* maps $\mathbb{RP}^n \dashrightarrow S^m$.

Remark:

This problem is very difficult. A special case of it is the following

Problem (Hurwitz, 1898)

Describe all triples of integers (r, s, n) such that

$$(x_1^2 + \cdots + x_r^2)(y_1^2 + \cdots + y_s^2) = z_1^2 + \cdots + z_n^2,$$

where z_i are some bilinear combinations of x_j and y_k .

The Hurwitz problem

Problem (Hurwitz, 1898)

Describe all triples of integers (r, s, n) such that

$$(x_1^2 + \cdots + x_r^2)(y_1^2 + \cdots + y_s^2) = z_1^2 + \cdots + z_n^2,$$

where z_i are some bilinear combinations of x_j and y_k .

Example

$(2,2,2)$ = multiplication of complex numbers.

$(4,4,4)$ = multiplication of quaternions.

$(8,8,8)$ = multiplication of octonions.

(r, n, n) = representations of Clifford algebras.

The Hurwitz problem

Problem (Hurwitz, 1898)

Describe all triples of integers (r, s, n) such that

$$(x_1^2 + \cdots + x_r^2)(y_1^2 + \cdots + y_s^2) = z_1^2 + \cdots + z_n^2,$$

where z_i are some bilinear combinations of x_j and y_k .

Example

$(2,2,2)$ = multiplication of complex numbers.

$(4,4,4)$ = multiplication of quaternions.

$(8,8,8)$ = multiplication of octonions.

(r, n, n) = representations of Clifford algebras.

The Hurwitz problem

Problem (Hurwitz, 1898)

Describe all triples of integers (r, s, n) such that

$$(x_1^2 + \cdots + x_r^2)(y_1^2 + \cdots + y_s^2) = z_1^2 + \cdots + z_n^2,$$

where z_i are some bilinear combinations of x_j and y_k .

Example

$(2,2,2)$ = multiplication of complex numbers.

$(4,4,4)$ = multiplication of quaternions.

$(8,8,8)$ = multiplication of octonions.

(r, n, n) = representations of Clifford algebras.

The Hurwitz problem

Problem (Hurwitz, 1898)

Describe all triples of integers (r, s, n) such that

$$(x_1^2 + \cdots + x_r^2)(y_1^2 + \cdots + y_s^2) = z_1^2 + \cdots + z_n^2,$$

where z_i are some bilinear combinations of x_j and y_k .

Example

$(2,2,2)$ = multiplication of complex numbers.

$(4,4,4)$ = multiplication of quaternions.

$(8,8,8)$ = multiplication of octonions.

(r, n, n) = representations of Clifford algebras.

The Hurwitz problem

Problem (Hurwitz, 1898)

Describe all triples of integers (r, s, n) such that

$$(x_1^2 + \cdots + x_r^2)(y_1^2 + \cdots + y_s^2) = z_1^2 + \cdots + z_n^2,$$

where z_i are some bilinear combinations of x_j and y_k .

Example

$(2,2,2)$ = multiplication of complex numbers.

$(4,4,4)$ = multiplication of quaternions.

$(8,8,8)$ = multiplication of octonions.

(r, n, n) = representations of Clifford algebras.

The Hurwitz problem

Problem (Hurwitz, 1898)

Describe all triples of integers (r, s, n) such that

$$(x_1^2 + \cdots + x_r^2)(y_1^2 + \cdots + y_s^2) = z_1^2 + \cdots + z_n^2,$$

where z_i are some bilinear combinations of x_j and y_k .

Example

$(2,2,2)$ = multiplication of complex numbers.

$(4,4,4)$ = multiplication of quaternions.

$(8,8,8)$ = multiplication of octonions.

(r, n, n) = representations of Clifford algebras.

Fractional quadratic transformations in terms of Hurwitz formulas

Set

$$X = (x_1, \dots, x_r), \quad Y = (y_1, \dots, y_s), \quad Z = (z_1, \dots, z_n).$$

Then

$$Q[X, Y] = \left(\frac{2Z}{|X|^2 + |Y|^2}, \frac{|X|^2 - |Y|^2}{|X|^2 + |Y|^2} \right)$$

is a fractional quadratic map from $\mathbb{R}P^{r+s-1}$ to S^n .

Some similar problems

Problem

Describe all maps that take one nice class of curves to another nice class of curves.

E.g.

Problem

*Describe all maps that take all **lines to conics**.*

Problem

*Describe all maps that take all **lines to plane curves**.*

Some similar problems

Problem

Describe all maps that take one nice class of curves to another nice class of curves.

E.g.

Problem

*Describe all maps that take all **lines to conics**.*

Problem

*Describe all maps that take all **lines to plane curves**.*

Some similar problems

Problem

Describe all maps that take one nice class of curves to another nice class of curves.

E.g.

Problem

*Describe all maps that take all **lines to conics**.*

Problem

*Describe all maps that take all **lines to plane curves**.*

Planarizations

Definition

Let $U \subset \mathbb{RP}^2$ be an open subset, and $F : U \rightarrow \mathbb{RP}^3$ a sufficiently smooth map such that $F(U \cap L)$ lies in a plane for every line $L \subset \mathbb{RP}^2$. Then F is called a **planarization**.

Theorem

For every planarization $F : U \rightarrow \mathbb{RP}^3$, there exists an open subset $U' \subset U$ such that one of the following:

- $F|_{U'}$ is trivial ($F(U')$ lies in a line)*
- $F|_{U'}$ is co-trivial (planes containing $F(U' \cap L)$ have a common point)*
- $F|_{U'}$ is a rational map of degree at most three.*

Planarizations

Definition

Let $U \subset \mathbb{RP}^2$ be an open subset, and $F : U \rightarrow \mathbb{RP}^3$ a sufficiently smooth map such that $F(U \cap L)$ lies in a plane for every line $L \subset \mathbb{RP}^2$. Then F is called a **planarization**.

Theorem

For every planarization $F : U \rightarrow \mathbb{RP}^3$, there exists an open subset $U' \subset U$ such that one of the following:

- $F|_{U'}$ is trivial ($F(U')$ lies in a line)
- $F|_{U'}$ is co-trivial (planes containing $F(U' \cap L)$ have a common point)
- $F|_{U'}$ is a rational map of degree at most three.

Planarizations

Definition

Let $U \subset \mathbb{RP}^2$ be an open subset, and $F : U \rightarrow \mathbb{RP}^3$ a sufficiently smooth map such that $F(U \cap L)$ lies in a plane for every line $L \subset \mathbb{RP}^2$. Then F is called a **planarization**.

Theorem

For every planarization $F : U \rightarrow \mathbb{RP}^3$, there exists an open subset $U' \subset U$ such that one of the following:

- $F|_{U'}$ is trivial ($F(U')$ lies in a line)
- $F|_{U'}$ is co-trivial (planes containing $F(U' \cap L)$ have a common point)
- $F|_{U'}$ is a rational map of degree at most three.

Planarizations

Definition

Let $U \subset \mathbb{RP}^2$ be an open subset, and $F : U \rightarrow \mathbb{RP}^3$ a sufficiently smooth map such that $F(U \cap L)$ lies in a plane for every line $L \subset \mathbb{RP}^2$. Then F is called a **planarization**.

Theorem

For every planarization $F : U \rightarrow \mathbb{RP}^3$, there exists an open subset $U' \subset U$ such that one of the following:

- $F|_{U'}$ is trivial ($F(U')$ lies in a line)
- $F|_{U'}$ is co-trivial (planes containing $F(U' \cap L)$ have a common point)
- $F|_{U'}$ is a rational map of degree at most three.

Planarizations

Definition

Let $U \subset \mathbb{RP}^2$ be an open subset, and $F : U \rightarrow \mathbb{RP}^3$ a sufficiently smooth map such that $F(U \cap L)$ lies in a plane for every line $L \subset \mathbb{RP}^2$. Then F is called a **planarization**.

Theorem

For every planarization $F : U \rightarrow \mathbb{RP}^3$, there exists an open subset $U' \subset U$ such that one of the following:

- *$F|_{U'}$ is trivial ($F(U')$ lies in a line)*
- *$F|_{U'}$ is co-trivial (planes containing $F(U' \cap L)$ have a common point)*
- *$F|_{U'}$ is a rational map of degree at most three.*

Linear webs of conics

Let \mathcal{L} be a linear system of conics of dimension 3 (a linear web of conics).

Theorem

Suppose that $f : U \rightarrow \mathbb{RP}^2$ is a sufficiently smooth map such that $f(U \cap L)$ is contained in a conic from \mathcal{L} for every line L . Then there is an open subset $U' \subset U$ such that one of the following:

- *$f(U')$ lies in a conic from \mathcal{L}*
- *$f|_{U'}$ is a quadratic rational map*
- *$f|_{U'}$ is a local inverse of a quadratic rational map*
- *$f|_{U'} = \Phi^{-1} \circ F$, where F and Φ are fractional quadratic maps to an irreducible quadric $S \subset \mathbb{RP}^3$*

Linear webs of conics

Let \mathcal{L} be a linear system of conics of dimension 3 (a linear web of conics).

Theorem

Suppose that $f : U \rightarrow \mathbb{RP}^2$ is a sufficiently smooth map such that $f(U \cap L)$ is contained in a conic from \mathcal{L} for every line L . Then there is an open subset $U' \subset U$ such that one of the following:

- *$f(U')$ lies in a conic from \mathcal{L}*
- *$f|_{U'}$ is a quadratic rational map*
- *$f|_{U'}$ is a local inverse of a quadratic rational map*
- *$f|_{U'} = \Phi^{-1} \circ F$, where F and Φ are fractional quadratic maps to an irreducible quadric $S \subset \mathbb{RP}^3$*

Linear webs of conics

Let \mathcal{L} be a linear system of conics of dimension 3 (a linear web of conics).

Theorem

Suppose that $f : U \rightarrow \mathbb{RP}^2$ is a sufficiently smooth map such that $f(U \cap L)$ is contained in a conic from \mathcal{L} for every line L . Then there is an open subset $U' \subset U$ such that one of the following:

- *$f(U')$ lies in a conic from \mathcal{L}*
- *$f|_{U'}$ is a quadratic rational map*
- *$f|_{U'}$ is a local inverse of a quadratic rational map*
- *$f|_{U'} = \Phi^{-1} \circ F$, where F and Φ are fractional quadratic maps to an irreducible quadric $S \subset \mathbb{RP}^3$*

Linear webs of conics

Let \mathcal{L} be a linear system of conics of dimension 3 (a linear web of conics).

Theorem

Suppose that $f : U \rightarrow \mathbb{RP}^2$ is a sufficiently smooth map such that $f(U \cap L)$ is contained in a conic from \mathcal{L} for every line L . Then there is an open subset $U' \subset U$ such that one of the following:

- *$f(U')$ lies in a conic from \mathcal{L}*
- *$f|_{U'}$ is a quadratic rational map*
- *$f|_{U'}$ is a local inverse of a quadratic rational map*
- *$f|_{U'} = \Phi^{-1} \circ F$, where F and Φ are fractional quadratic maps to an irreducible quadric $S \subset \mathbb{RP}^3$*

Linear webs of conics

Let \mathcal{L} be a linear system of conics of dimension 3 (a linear web of conics).

Theorem

Suppose that $f : U \rightarrow \mathbb{RP}^2$ is a sufficiently smooth map such that $f(U \cap L)$ is contained in a conic from \mathcal{L} for every line L . Then there is an open subset $U' \subset U$ such that one of the following:

- *$f(U')$ lies in a conic from \mathcal{L}*
- *$f|_{U'}$ is a quadratic rational map*
- *$f|_{U'}$ is a local inverse of a quadratic rational map*
- *$f|_{U'} = \Phi^{-1} \circ F$, where F and Φ are fractional quadratic maps to an irreducible quadric $S \subset \mathbb{RP}^3$*

Rectifiable pencils of conics

Theorem

*Suppose that a local analytic diffeomorphism $f : (\mathbb{C}^2, 0) \rightarrow (\mathbb{C}^2, 0)$ takes all lines through 0 to **conics** and satisfies a minor non-degeneracy assumption. Then, for all lines $l \ni 0$, the conic $f(l)$ has 3 points of tangency with a curve of class 3 (i.e. dual curve to a cubic).*